Generalization of the Derivative Analysis Method to Non-Stationary Sinusoidal Modeling

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sound signal represented as a sum of sinusoids controlled in amplitude and frequency (or phase)

(short-term) stationarity hypothesis

amplitude and frequency parameters considered as constant within one (short-time) analysis frame

- \rightarrow numerous (STFT-based) analysis methods. . .
 - parabolic interpolation [Smith & Serra (ICMC 1987)]
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[McAulay & Quatieri (IEEE Trans. ASSP 1986)] [Serra & Smith (Computer Music Journal 1990)]

The (analytic) audio signal *s* is given by:

$$s(t) = \sum_{p=1}^{P} a_p(t) \exp(\phi_p(t))$$
 with $\frac{d\phi_p}{dt}(t) = \omega_p(t)$

where *P* is the number of **partials**.

The functions a_p , ω_p , and ϕ_p are the instantaneous amplitude, frequency, and phase of the p^{th} partial, respectively.

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Trajectories of the Partials



Frequencies and amplitudes, as functions of time, of the partials of an alto saxophone sound, during \approx 1.5s

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For one partial (P = 1), for one frame (centered on time t = 0):

$$s(t) = \exp\left(\underbrace{(\lambda_0 + \mu_0 t)}_{\lambda(t) = \log(a(t))} + j\underbrace{\left(\phi_0 + \omega_0 t + \frac{\psi_0}{2}t^2\right)}_{\phi(t)}\right)$$

- \rightarrow How to estimate the instantaneous parameters (at t = 0)?
 - amplitude $\exp(\lambda_0) = a_0$
 - amplitude modulation μ_0 • phase ϕ_0
 - frequency ω_0 • frequency modulation ψ_0

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(**NB:** the stationary case is when $\mu_0 = \psi_0 = 0$)

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Short-Term Fourier Transform

$$S_{w}(t,\omega) = \int_{-\infty}^{+\infty} s(\tau)w(\tau-t)\exp\left(-j\omega(\tau-t)\right) d\tau$$



using local maxima m of short-term magnitude spectrum

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Analysis Window w (e.g. Hann window)

w with finite time support and **band-limited in frequency**: for one peak corresponding to one specific partial, the influence of the other partials can be neglected (in the general case when P > 1)

$$S_{w}(0,\omega) = \underbrace{a_{0}e^{j\phi_{0}}}_{s_{0}} \cdot \Gamma_{w}(\omega_{0} - \omega, \mu_{0}, \psi_{0}) \quad \text{where}$$

$$\Gamma_{w}(\omega,\mu_{0},\psi_{0}) = \int_{-\infty} w(t) \exp\left(\mu_{0}t + j\left(\omega t + \frac{\varphi_{0}}{2}t^{2}\right)\right) dt$$

(**NB:** in the stationary case where $\Gamma_w(\omega_0 - \omega, 0, 0) = W(\omega - \omega_0)$, the peak corresponds to the spectrum *W* of the analysis window centered on frequency ω_0 and scaled by the complex amplitude s_0)



Reassignment Method

$$\hat{\omega}_{0} = \hat{\omega}(0, \omega_{m}) \quad \text{where} \quad \hat{\omega}(t, \omega) = \omega - \Im \left(\frac{S_{w'}(t, \omega)}{S_{w}(t, \omega)} \right)$$

$$\hat{\mu}_{0} = \hat{\mu}(0, \omega_{m}) \quad \text{where} \quad \hat{\mu}(t, \omega) = -\Re \left(\frac{S_{w'}(t, \omega)}{S_{w}(t, \omega)} \right)$$

$$\hat{\psi}_{0} = \hat{\psi}(0, \omega_{m}) \quad \text{where} \quad \hat{\psi} = \frac{\Im \left(\frac{S_{w'}}{S_{w}} \right) - \Im \left(\left(\frac{S_{w'}}{S_{w}} \right)^{2} \right)}{\Re \left(\frac{S_{w}S_{w'}}{S_{w}^{2}} \right) - \Re \left(\frac{S_{w'}}{S_{w}} \right)}$$
nally
$$\hat{a}_{0} = \left| \frac{S_{w}(\omega_{m})}{\Gamma_{w}(\Delta_{\omega}, \hat{\mu}_{0}, \hat{\psi}_{0})} \right| \quad \text{and} \quad \hat{\phi}_{0} = \angle \left(\frac{S_{w}(\omega_{m})}{\Gamma_{w}(\Delta_{\omega}, \hat{\mu}_{0}, \hat{\psi}_{0})} \right)$$

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$$\hat{\mu}_{0} = \left|\frac{S_{W}(\omega_{m})}{\Gamma_{W}(\Delta_{\omega}, \hat{\mu}_{0}, \hat{\psi}_{0})}\right| \quad \text{and} \quad \hat{\phi}_{0} = 2\left(\frac{S_{W}(\omega_{m})}{\Gamma_{W}(\Delta_{\omega}, \hat{\mu}_{0}, \hat{\psi}_{0})}\right)$$

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uses the derivatives of the signal (the derivative of an exponential is an exponential...)

$$\boldsymbol{s}'(t) = \left(\mu_0 + \boldsymbol{j}(\omega_0 + \psi_0 t)\right) \cdot \boldsymbol{s}(t)$$

 $j\psi_0 t$ is an odd function \implies its spectrum is real...

$$\hat{\omega}_0 = \Im\left(\frac{S'_w}{S_w}(\omega_m)\right)$$

moreover, its spectrum is null at frequency zero...

$$\hat{\mu}_0 = \Re\left(\frac{S'_w}{S_w}(\hat{\omega}_0)\right)$$

(NB: in theory, equivalent to spectral reassignment estimators)



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Conclusion

Frequency Modulation $\hat{\psi}_0$

with the second derivative...

$$s''(t) = (\mu_0^2 - \omega_0^2 - 2\omega_0\psi_0t - \psi_0^2t^2) + j(\psi_0 + 2\mu_0\omega_0 + 2\mu_0\psi_0t) \cdot s(t)$$

using the same kind of properties...

$$\hat{\psi}_0 = \Im\left(\frac{S_w''}{S_w}(\hat{\omega}_0)\right) - 2\hat{\mu}_0\hat{\omega}_0.$$

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Amplitude \hat{a}_0 and Phase $\hat{\phi}_0$

finally

$$\hat{a}_{0} = \left| \frac{S_{w}(\hat{\omega}_{0})}{\Gamma_{w}(0, \hat{\mu}_{0}, \hat{\psi}_{0})} \right|$$
$$\hat{\phi}_{0} = \angle \left(\frac{S_{w}(\hat{\omega}_{0})}{\Gamma_{w}(0, \hat{\mu}_{0}, \hat{\psi}_{0})} \right)$$

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practical problem:

How to get the derivatives s' from the (discrete-time) signal s?

$$s'(t) = \lim_{\epsilon \to 0} \frac{s(t+\epsilon) - s(t)}{\epsilon}$$

a bad idea: approximate it by the difference (\$\varepsilon = 1/F_s\$)
a good idea: use the ideal differentiator filter...

$$h[n] = F_s \frac{(-1)^n}{n}$$
 for $n \neq 0$, and $h[0] = 0$

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... windowed by the Hann window (of length 1023)



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Discrete Derivative



(high frequencies – above 3/4 Nyquist – are problematic)

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3 methods tested:

- reassignment (R)
- 2 flavors of the derivative (D)

(the champion) (the challenger)

- TD: theoretic derivative (derivative known analytically)
- ED: estimated derivative (with the differentiator filter *h*)

(frame size N = 511, sampling frequency $F_s = 44100$ Hz)

 \rightarrow estimation precision for each parameter, compared to the Cramér-Rao Bound (CRB) (the best performance achievable by an unbiased estimator), in presence of Gaussian white noise with various SNRs;



with 5 parameters to test...

- ω_0 : 99 frequencies linearly distributed in (0, 3 $F_s/8$)Hz,
- ϕ_0 : 9 phases linearly distributed in the $(-\pi, +\pi)$ interval,
- μ₀: either 0 (stationary case) or in [-100, +100] (AM),
- ψ_0 : either 0 (stationary case) or in [-10000, +10000] (FM),
- amplitude *a*₀ set to 1.

(conditions similar to [Betser *et al.* (IEEE Trans. SP 2008)], where the reassignment performs best, at least regarding frequency estimation)

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Results: Amplitude \hat{a}_0



D performs better in the non-stationary case

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Results: Amplitude Modulation $\hat{\mu}_0$



D performs better in the non-stationary case

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Results: Frequency $\hat{\omega}_0$



although R and ED perform equally, TD indicates that ED can beat R in the stationary case, with a better derivative

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Results: Frequency Modulation $\hat{\psi}_0$



R performs better in the non-stationary case

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Summary:

- the derivative method is generalized to the non-stationary case,
- computing the discrete derivative is not a problem anymore,
- the derivative method outperforms the reassignment method in all cases except for the estimation of the frequency modulation.

Future Work:

- understand why the reassignment method is better in this case,
- study the behavior of the methods in more complex AM/FM conditions (such as sinusoidal tremolo/vibrato),
- propose a very fast algorithm for the new method...