

Table of Contents

List of Symbols	12
List of Abbreviations	15
1 Introduction	17
1.1 Historical Notes.....	17
1.2 Overview of the Work.....	20
1.3 Contributions of the Author	21
1.4 Related Publications.....	22
2 Digital Waveguide Modeling	25
2.1 Waveguide Modeling of Strings	25
2.1.1 Wave Equation and the Traveling Wave Solution	25
2.1.2 Incorporating Losses and Dispersion	26
2.1.3 Karplus–Strong Algorithm and Its Extensions.....	27
2.1.4 Calibration of the Waveguide String Model	29
2.1.5 Excitation Signal of the Waveguide String Model.....	32
2.1.6 Discussion	33
2.2 Waveguide Modeling of Cylindrical Tubes.....	34
2.2.1 The One-Dimensional Wave Equation.....	35
2.2.2 A Model Composed of Coupled Uniform Tube Sections	35
2.2.3 KL Scattering Junction for Volume Velocity Waves.....	36
2.2.4 KL Scattering Junction for Pressure Waves.....	38
2.2.5 Boundary Conditions of a Cylindrical Tube	39
2.2.6 General Properties of the Cylindrical Tube Model	40
2.2.7 Sparse Tube Model.....	41
2.2.8 Extensions to the Basic KL Model.....	42
2.3 Junction of Three Acoustic Tubes	42
2.3.1 Three-Port Scattering Junction for Volume Velocity.....	43
2.3.2 Three-Port Scattering Junction for Sound Pressure	44
2.3.3 Side Branch in a Uniform Tube	45
2.4 Waveguide Modeling of Conical Tubes	48
2.4.1 Traveling Wave Solution for Spherical Waves	49
2.4.2 Junction of Conical Tube Sections	50
2.4.3 Reflection Function with Taper Discontinuity Only	52
2.4.4 Closed and Open End of a Truncated Conical Tube	53
2.4.5 Discrete-Time Reflection and Transmission Filters.....	54
2.4.6 Stability of the Reflection Filter	56
2.4.7 Modeling the Ends of a Conical Tube.....	56
2.4.8 Conclusions and Discussion.....	57
2.5 Waveguide Models for Wind Instruments	58
2.5.1 Need for Finger-Hole Models	59
2.5.2 Modeling of a Single Woodwind Finger Hole	59
2.5.3 Discrete-Time Scattering Junction	61
2.6 Relation to Other Methods	62

2.6.1	Comparison of Waveguide Filters and Wave Digital Filters	63
2.6.2	Reverberation and Simulation of Room Acoustics	63
2.7	Conclusions	64
3	Fractional Delay Filters	65
3.1	Ideal Fractional Delay	65
3.1.1	Continuous-Time System for Arbitrary Delay	65
3.1.2	Discrete-Time System for Arbitrary Delay	66
3.1.3	Fractional Delay and Shannon Reconstruction	68
3.1.4	Characteristics of the Ideal Fractional Delay Element	69
3.1.5	Conclusion and Discussion	71
3.2	Design Methods for Fractional Delay FIR Filters	71
3.2.1	Least Squared Integral Error Design	72
3.2.2	LS Design with Reduced Bandwidth	75
3.2.3	Windowing the Ideal Impulse Response	75
3.2.4	General Least Squares FIR Approximation of a Complex Frequency Response	76
3.2.5	Minimax Design of FIR FD Filters	79
3.2.6	Other Methods for the Design of FIR FD Filters	81
3.3	Maximally Flat FD FIR Filter: Lagrange Interpolation	82
3.3.1	Derivation of the Maximally Flat Fractional Delay FIR Filter	82
3.3.2	Classical Approach	84
3.3.3	Symmetry of the Lagrange Interpolation Coefficients	85
3.3.4	Computation of Coefficients for a Lagrange Interpolator	86
3.3.5	Windowing Approach to Lagrange Interpolation	87
3.3.6	Approximation Errors of Lagrange Interpolation	90
3.3.7	Farrow Structure of Lagrange Interpolation	95
3.3.8	Related Polynomial Interpolation Techniques	102
3.3.9	Conclusion and Discussion	103
3.4	Design Methods for Fractional Delay Allpass Filters	105
3.4.1	Properties of the Discrete-Time Allpass Filter	105
3.4.2	Design of Fractional Delay Allpass Filters	106
3.4.3	Maximally Flat Group Delay Design of FD Allpass Filters	107
3.4.4	Choice of Optimal Range for D in the Thiran Interpolator	110
3.4.5	Discussion	113
3.5	Time-Varying Fractional Delay Filters	114
3.5.1	Consequences of Changing Filter Coefficients	114
3.5.2	Implementation of a Variable Delay Using FIR Filters	114
3.5.3	Transients in Time-Varying Recursive FD Filters	116
3.5.4	Transient Elimination Methods for Time-Varying Recursive Filters ...	117
3.5.5	A Novel and Efficient Method for Elimination of Transients	121
3.5.6	Examples with a Time-Varying Thiran Allpass Filter	125
3.6	Conclusions	126

4 Fractional Delay Waveguide Filters	128
4.1 Deinterpolation.....	128
4.1.1 Introduction to Deinterpolation	128
4.1.2 Deinterpolation Versus Interpolation	130
4.1.3 Implementing Deinterpolation Using an FIR Filter	131
4.1.4 Adding a Signal to a Fractional Point of a Delay Line Using an FIR Deinterpolator.....	133
4.1.5 Discussion	134
4.2 Fractional Delay Waveguide Systems	135
4.2.1 Variable-Length Digital Waveguide	135
4.2.2 Connecting Waveguides at Arbitrary Points	136
4.3 Interpolated Waveguide Tube Model	137
4.3.1 Interpolated Scattering Junction	138
4.3.2 Implementing the FD Scattering Junction Using FIR Filters	140
4.3.3 Transfer Functions of FIR Interpolators and Deinterpolators	142
4.3.4 Choice of FIR FD Filter Design	144
4.3.5 Reflection and Transmission Functions	145
4.3.6 Analysis of Errors Due to FD Approximation	148
4.3.7 Simulation of a Two-Tube System Using FIR FD Filters.....	150
4.3.8 Conclusion.....	153
4.4 Interpolated Finger-Hole Model	153
4.4.1 FIR-Type Fractional-Delay Finger-Hole Model	154
4.4.2 Approximation Error Due to FD Filters	155
4.4.3 Implementation Issues	157
4.5 Fractional Delay Operations with Allpass Filters	158
4.5.1 Implementing a Variable Delay Line Using an Allpass Filter	158
4.5.2 Implementing Interpolation and Deinterpolation with Allpass Filters..	159
4.6 Interpolated Waveguide Model: Allpass Filter Approach	160
4.6.1 Derivation of the Allpass Fractional Delay Junction	160
4.6.2 Approximation Errors due to an Allpass Fractional Delay Junction.....	162
4.6.3 Simulation of a Two-Tube Model with Allpass Filters.....	163
4.6.4 Alternative Allpass Filter Structure.....	165
4.7 Allpass Fractional Delay Finger-Hole Model	166
4.8 Conclusions	168
5 Conclusions and Further Research	169
5.1 Summary and Conclusions.....	169
5.2 Suggestions for Future Work	170
References	172
Appendix A. Bandlimited Squared Integral Error of FIR FD Filters	184
Appendix B. Effective Length of the Infinite Impulse Response	186
Index	193